# Connor Thomas Green

## Contact

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# Education

Harvard University 2014-2018 S.B. Mechanical Engineering Norwegian Masters equivalent Cumulative GPA: 3.6

# **Key Skills**

Native English Fluent Norwegian

#### CAD/CAM/FEA

Inventor (10+ yrs)
Solidworks (6 yrs)
Simens NX
AutoCAD
ANSYS
Abaqus
Nastran
Fusion
MasterCAM
COMSOL

3D Printing

**Programming** 

Matlab Microsoft SSMS & Access Python C

Part Time Watchmaker

Full time tinkerer

# **Work Experience**

2025 - Present

Special Product Designer • Silent Tools • Sandvik Coromant Special Product Creation

 Designed, tested, and created manufacturing documentation of special silent tools for turning and milling

2018 - 2025

Product Engineer • R&D Skis • Madshus AS

<u>Product development highlight – 2024 Redline Series</u>

- Reduced weight by 20%
- Decreased prime costs 18%
- Responsible for all design and documentation

# Product line development – knowing the consumer

- Transitioned the 2021 ski line strategy from "good-better-best" to a "best product for each target user"
- Immediately led to test winning products in the recreational and overall segments from UTE and Dinside, respectively

# <u>Factory improvements – increasing efficiency and quality</u>

- Developed an algorithm and accompanying app to increase the percentege of skis within tolerance from <30% to over 95%</li>
- Built a progam to standardize cambers during production allowing for real-time adjustments and improved quality

Summer 2017

Internship • Silicon Wafer Metrology • Nanometrics

- Responsible for laboratory research and QC validation
- Solved an XY stage issue, improving optical precision 10x across the wafer surface to < 50 $\mu m$

Summer 2016

Internship • Wireless Braking Rollerskis • Rollersafe AS

- Streamlined production and managed the testing program

### **Achievements**

- Harvard Skiing NCAA Team Captain 2017-2018
- Member of the Order of the Engineer
- Winner of the ES51 Harvard Turf Wars Robotics Competition
- Researcher for Octopus Arm-Inspired Tapered Soft Actuators with Suckers for Improved Grasping published in Soft Robotics 2020